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Identification of Nonlinear Systems Using Neural Networks and Polynomial Models

A Block-Oriented Approach



Springer

Identification Of Nonlinear Systems Using Neural Networks And Polynomial Models Blockoriented Approach

Azar, Ahmad Taher



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Identification of Nonlinear Systems Using Neural Networks and Polynomial Models Andrzej Janczak, 2009-09-02

This monograph systematically presents the existing identification methods of nonlinear systems using the block oriented approach. It surveys various known approaches to the identification of Wiener and Hammerstein systems which are applicable to both neural network and polynomial models. The book gives a comparative study of their gradient approximation accuracy, computational complexity and convergence rates and furthermore presents some new and original methods concerning the model parameter adjusting with gradient based techniques. *Identification of Nonlinear Systems Using Neural Networks and Polynomial Models* is useful for researchers, engineers and graduate students in nonlinear systems and neural network theory.

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Block-oriented Nonlinear System Identification Fouad Giri, Er-Wei Bai, 2010-09-22 Block oriented Nonlinear System Identification deals with an area of research that has been very active since the turn of the millennium. The book makes a pedagogical and cohesive presentation of the methods developed in that time. These include iterative and over parameterization techniques, stochastic and frequency approaches, support vector machine, subspace and separable least squares methods, blind identification method, bounded error method and decoupling inputs approach. The identification methods are presented by authors who have either invented them or contributed significantly to their development. All the important issues, e.g. input design, persistent excitation and consistency analysis, are discussed. The practical relevance of block oriented models is illustrated through biomedical physiological system modelling. The book will be of major interest to all those who are concerned with nonlinear system identification whatever their activity areas. This is particularly the case for educators in electrical, mechanical, chemical and biomedical engineering and for practising engineers in process, aeronautic, aerospace, robotics and vehicles control. *Block oriented Nonlinear System Identification* serves as a reference for active researchers, newcomers, industrial and education practitioners and graduate students alike.

Nonlinear Predictive Control Using Wiener Models Maciej Ławryńczuk, 2021-09-21 This book presents computationally efficient MPC solutions. The classical model predictive control (MPC) approach to control dynamical systems described by the Wiener model uses an inverse static block to cancel the influence of process nonlinearity. Unfortunately, the model's structure

is limited and it gives poor control quality in the case of an imperfect model and disturbances. An alternative is to use the computationally demanding MPC scheme with on line nonlinear optimisation repeated at each sampling instant. A linear approximation of the Wiener model or the predicted trajectory is found on line. As a result quadratic optimisation tasks are obtained. Furthermore parameterisation using Laguerre functions is possible to reduce the number of decision variables. Simulation results for ten benchmark processes show that the discussed MPC algorithms lead to excellent control quality. For a neutralisation reactor and a fuel cell essential advantages of neural Wiener models are demonstrated.

Handbook of Research on Advanced Intelligent Control Engineering and Automation Azar, Ahmad Taher, 2014-11-30 In industrial engineering and manufacturing control of individual processes and systems is crucial to developing a quality final product. Rapid developments in technology are pioneering new techniques of research in control and automation with multi disciplinary applications in electrical electronic chemical mechanical aerospace and instrumentation engineering. The Handbook of Research on Advanced Intelligent Control Engineering and Automation presents the latest research into intelligent control technologies with the goal of advancing knowledge and applications in various domains. This text will serve as a reference book for scientists engineers and researchers as it features many applications of new computational and mathematical tools for solving complicated problems of mathematical modeling simulation and control.

Neural Network Modeling and Identification of Dynamical Systems Yury Tiumentsev, Mikhail Egorchev, 2019-05-17 Neural Network Modeling and Identification of Dynamical Systems presents a new approach on how to obtain the adaptive neural network models for complex systems that are typically found in real world applications. The book introduces the theoretical knowledge available for the modeled system into the purely empirical black box model thereby converting the model to the gray box category. This approach significantly reduces the dimension of the resulting model and the required size of the training set. This book offers solutions for identifying controlled dynamical systems as well as identifying characteristics of such systems in particular the aerodynamic characteristics of aircraft. Covers both types of dynamic neural networks black box and gray box including their structure synthesis and training. Offers application examples of dynamic neural network technologies primarily related to aircraft. Provides an overview of recent achievements and future needs in this area.

Electromagnetic Fields in Mechatronics, Electrical and Electronic Engineering Andrzej Krawczyk, Sławomir Wiak, Xose M. Lopez-Fernandez, 2006 More and more researchers engage into investigation of electromagnetic applications especially these connected with mechatronics information technologies medicine biology and material sciences. It is readily seen when looking at the content of the book that computational techniques which were under development during the last three decades and are still being developed serve as good tools for discovering new electromagnetic phenomena. It means that the field of computational electromagnetics belongs to an application area rather than to a research area. This publication aims at joining theory and practice thus the majority of papers are deeply rooted in engineering problems being simultaneously of high

theoretical level The editors hope to touch the heart of the matter in electromagnetism The book focuses on the following issues Computational Electromagnetics Electromagnetic Engineering Coupled Field and Special Applications Micro and Special Devices Bioelectromagnetics and Electromagnetic Hazard and Magnetic Material Modelling Abstracted in Inspec

Computationally Efficient Model Predictive Control Algorithms Maciej Ławryńczuk, 2014-01-24 This book thoroughly discusses computationally efficient suboptimal Model Predictive Control MPC techniques based on neural models The subjects treated include A few types of suboptimal MPC algorithms in which a linear approximation of the model or of the predicted trajectory is successively calculated on line and used for prediction Implementation details of the MPC algorithms for feed forward perceptron neural models neural Hammerstein models neural Wiener models and state space neural models The MPC algorithms based on neural multi models inspired by the idea of predictive control The MPC algorithms with neural approximation with no on line linearization The MPC algorithms with guaranteed stability and robustness Cooperation between the MPC algorithms and set point optimization Thanks to linearization or neural approximation the presented suboptimal algorithms do not require demanding on line nonlinear optimization The presented simulation results demonstrate high accuracy and computational efficiency of the algorithms For a few representative nonlinear benchmark processes such as chemical reactors and a distillation column for which the classical MPC algorithms based on linear models do not work properly the trajectories obtained in the suboptimal MPC algorithms are very similar to those given by the ideal MPC algorithm with on line nonlinear optimization repeated at each sampling instant At the same time the suboptimal MPC algorithms are significantly less computationally demanding

Artificial Neural Networks for the Modelling and Fault Diagnosis of Technical Processes Krzysztof Patan, 2008-06-11 An unappealing characteristic of all real world systems is the fact that they are vulnerable to faults malfunctions and more generally unexpected modes of behaviour This explains why there is a continuous need for reliable and universal monitoring systems based on suitable and effective fault diagnosis strategies This is especially true for engineering systems whose complexity is permanently growing due to the inevitable development of modern industry as well as the information and communication technology revolution Indeed the design and operation of engineering systems require an increased attention with respect to availability reliability safety and fault tolerance Thus it is natural that fault diagnosis plays a fundamental role in modern control theory and practice This is reflected in plenty of papers on fault diagnosis in many control oriented conferences and journals Indeed a large amount of knowledge on model based fault diagnosis has been accumulated through scientific literature since the beginning of the 1970s As a result a wide spectrum of fault diagnosis techniques have been developed A major category of fault diagnosis techniques is the model based one where an analytical model of the plant to be monitored is assumed to be available

Advanced Neural Network-Based Computational Schemes for Robust Fault Diagnosis Marcin Mrugalski, 2013-08-04 The present book is devoted to problems of adaptation of artificial neural networks to robust fault diagnosis schemes It presents neural networks

based modelling and estimation techniques used for designing robust fault diagnosis schemes for non linear dynamic systems A part of the book focuses on fundamental issues such as architectures of dynamic neural networks methods for designing of neural networks and fault diagnosis schemes as well as the importance of robustness The book is of a tutorial value and can be perceived as a good starting point for the new comers to this field The book is also devoted to advanced schemes of description of neural model uncertainty In particular the methods of computation of neural networks uncertainty with robust parameter estimation are presented Moreover a novel approach for system identification with the state space GMDH neural network is delivered All the concepts described in this book are illustrated by both simple academic illustrative examples and practical applications

Theory, Methodology, Tools and Applications for Modeling and Simulation of Complex Systems Lin Zhang,Xiao Song,Yunjie Wu,2016-09-22 This four volume set CCIS 643 644 645 646 constitutes the refereed proceedings of the 16th Asia Simulation Conference and the First Autumn Simulation Multi Conference AsiaSim SCS AutumnSim 2016 held in Beijing China in October 2016 The 265 revised full papers presented were carefully reviewed and selected from 651 submissions The papers in this first volume of the set are organized in topical sections on modeling and simulation theory and methodology model engineering for system of systems high performance computing and simulation modeling and simulation for smart city

Automatic Control, Robotics, and Information Processing Piotr Kulczycki,Józef Korbicz,Janusz Kacprzyk,2020-09-03 This book presents a wide and comprehensive range of issues and problems in various fields of science and engineering from both theoretical and applied perspectives The desire to develop more effective and efficient tools and techniques for dealing with complex processes and systems has been a natural inspiration for the emergence of numerous fields of science and technology in particular control and automation and more recently robotics The contributions gathered here concern the development of methods and algorithms to determine best practices regarding broadly perceived decisions or controls From an engineering standpoint many of them focus on how to automate a specific process or complex system From a tools based perspective several contributions address the development of analytic and algorithmic methods and techniques devices and systems that make it possible to develop and subsequently implement the automation and robotization of crucial areas of human activity All topics discussed are illustrated with sample applications

Soft Computing in Industrial Applications X.Z. Gao,António Gaspar-Cunha,Mario Köppen,Jun Wang,Gerald Schaefer,2010-09-07 The 14th onlineWorld Conference on Soft Computing in Industrial Applications provides a unique opportunity for soft computing researchers and practitioners to publish high quality papers and discuss research issues in detail without incurring a huge cost The conference has established itself as a truly global event on the Internet The quality of the conference has improved over the years The WSC14 conference has covered new trends in soft computing to state of the art applications The conference has also added new features such as community tools syndication and multimedia online presentations

Analytical Methods in Fuzzy Modeling and Control Jacek Kluska,2009-01-22 This book is focused on

mathematical analysis and rigorous design methods for fuzzy control systems based on Takagi Sugeno fuzzy models sometimes called Takagi Sugeno Kang models , *Uncertainties in Acoustical Transfer Functions* Pascal Dietrich,2013 Measured transfer functions of acoustic systems are often used to derive single number parameters The uncertainty analysis is commonly focused on the derived parameters but not on the transfer function as the primary quantity This thesis presents an approach to assess the uncertainty contributions in these transfer functions by using analytic models Uncertainties caused by the measurement method are analyzed with a focus on the underlying signal processing In particular the influence of nonlinearities in the acoustic measurement chain are modeled to predict artifacts in the measured signals and hence the calculated acoustic transfer function Secondly characterization methods commonly applied in the field of signal processing are linked to the acoustic scenarios and the main influencing parameters Acoustic parameters are then derived analytically and by means of Monte Carlo simulations considering the uncertainty of these input parameters In order to provide airborne applications analytic models for sound barrier and room acoustic measurements are developed incorporating the directivity and the orientation of the sound source as well as the positions of sources and receivers The simulated uncertainty contributions are validated by measurements The same approach is also applied to structure borne sound applications

Proceedings. 24. Workshop Computational Intelligence, Dortmund, 27. - 28. November 2014 Hoffmann,

Frank,Huellermeier, E.,2014-11-20 **Robust and Fault-Tolerant Control** Krzysztof Patan,2019-03-16 Robust and Fault Tolerant Control proposes novel automatic control strategies for nonlinear systems developed by means of artificial neural networks and pays special attention to robust and fault tolerant approaches The book discusses robustness and fault tolerance in the context of model predictive control fault accommodation and reconfiguration and iterative learning control strategies Expanding on its theoretical deliberations the monograph includes many case studies demonstrating how the proposed approaches work in practice The most important features of the book include a comprehensive review of neural network architectures with possible applications in system modelling and control a concise introduction to robust and fault tolerant control step by step presentation of the control approaches proposed an abundance of case studies illustrating the important steps in designing robust and fault tolerant control and a large number of figures and tables facilitating the performance analysis of the control approaches described The material presented in this book will be useful for researchers and engineers who wish to avoid spending excessive time in searching neural network based control solutions It is written for electrical computer science and automatic control engineers interested in control theory and their applications This monograph will also interest postgraduate students engaged in self study of nonlinear robust and fault tolerant control

Challenges in Automation, Robotics and Measurement Techniques Roman Szewczyk,Cezary Zieliński,Małgorzata Kaliczyńska,2016-02-15 This book presents the set of papers accepted for presentation at the International Conference Automation held in Warsaw 2 4 March of 2016 It presents the research results presented by top experts in the fields of

industrial automation control robotics and measurement techniques Each chapter presents a thorough analysis of a specific technical problem which is usually followed by numerical analysis simulation and description of results of implementation of the solution of a real world problem The presented theoretical results practical solutions and guidelines will be valuable for both researchers working in the area of engineering sciences and for practitioners solving industrial problems Advances in Power and Energy Engineering Yuanzhang Sun,2016-04-05 Energy and power are playing pivotal roles in social and economic developments of the modern world Energy and power engineers and technologists have made our lives much more comfortable and affordable However due to the demands of the global population on resources and the environment innovations of more reliable and sustainable energy res

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