Control Relevant Identification of a Compact Disc Pick-up Mechanism

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Administratory,

This pager discusses the control relevant parametric identification of a serve system present in a Compact Disc player. In this application an approximate closed loop scientification problem is solved in order to come up with a linear multivariable discrete time model, saitable for control design. This identification problem is handled by a recently introduced two stage method. It yields an explicit and tunable expression for the bias distribution of the model being estimated, clearly showing the dynamics of the closed loop system in the (asymptotic) approximation criterion. This result will be exploited to identify the model in a control relevant way by additional data filtering. The recently introduced method in [28] for model sincertainty quantification is used to construct

1 Introduction

Compact Disc players use an optical decoding device to reproduce high quality and/so from a digitally coded signal, recorded as a spired track on a reflective disc, see also [2]. As increasing amount of equivalent optical devices will be used in portable applications, having severe allock disturbances. The track following properties of a CD player, operating in these conditions, could be improved by designing an enhanced multivariable controller. The intention of this paper is to estimate a (nominal) multivariable FDLTI (Finite Dimensional Linear Time Invariant) dynamical model, obtained from closed loop experiments, which can be used for control design. Additionally, the procedure presented in [20] is used for a quantification of the resulting model error by estimating a nonparametric additive model uncertainty.

There is a growing interest in merging the problems of control design and identification. On the one hand this is caused by the fact that from a robust control design point of view we require expressions for model uncertainty that have to be used in robust control design procedures. On the other hand the (nominal) models used to design control systems very often will have to be gathered by experimental methods.

Practically it is impossible to exactly characterize all phenomena that describe the dynamical behaviour of a physical system and the corresponding models will necessarily be approximative. Furthermore, control design methods can get unmanageable if they are applied to models of high complexity. Since the subdity of any approximate model hinger on its intended use, the identification procedure being applied will be subjected to several requirements, in order to provide estimated models that are suitable for control design. These considerations have resulted in the statement that the best model for control design cannot be derived from open loop experiments along [1, 16].

A control relevant identification requires that the relevant dysamical behaviour of the system is estimated while it operates in a closed loop configuration with the controller to be designed.

FThe work of Raymond de Calladon is spousored by the Dutch "Systems and Control Theory Network".

Some the controller obtained from the control design is (yet) unknown, this will generally lead to an iterative scheme of identification and control design, using the controller of step i = 1 to estimate a model for step i. This has led to study several different types of iterative achieves of identification and control design, use [6, 10, 11, 15, 17, 24]

In this paper we concentrate on one identification step in such an iterative procedure. Within the framework of prediction error identification [12] we will identify a multivariable control relevant approximate model, employing a number of recently introduced methods. An indirect (two-stage) method [19] will be employed to perform the approximate closed loop identification. The basic advantage of this approximate closed loop identification. The basic advantage of this approximate identification results, in which the asymptotic bias distribution of the identified model becomes an explicit and tunable expression that is independent of the (unknown) some disturbance on the data. Additional data filtering is applied to tune the approximation criterion to become a control relevant criterion.

The outline of this paper is as follows. First a concise description of the Compact Disc pick-up mechanism and the experimental set up is given in section 2. Next some preliminary notation is discussed. In section 4 we pay attention to the specific two-stage identification procedure, while is section 5 we discuss the use of orthonormal basis functions that are employed in the first stage of the procedure. Next, the control relevance of the identification approach is given attention and is section 6 we will present the experimental results.

2 Compact Disc Mechanism

The CD mechanism consists of a turn table DC-motor for the rotation of the Compact Disc and a radial arm in order to follow the track of the disc. Furthermore, an OPU (Optical Pickwap-Univ) is mounted on the end of the balanced radial arm to read the digitally coded signal, recorded on the disc. Schematically the CD mechanism is green in figure 1.

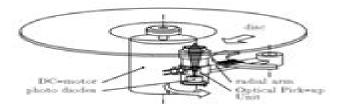


Fig. 1: Schematic view of CD mechanism

A diode generates a laser beam that passes through a series of optical lenses in the OPU to give a spot on the disc surface.

Anthony S. Fauci

Identification for Control Design with Application to a Compact Disk Mechanism Johannes Godfried Maria Dötsch, Hans Iterative Identification and Control Pedro Albertos, Antonio Sala Pigueras, 2012-12-06 An exposition of Dotsch, 1998-08-01 the interplay between the modelling of dynamic systems and the design of feedback controllers based on these models is the main goal of this book The combination of both subjects into a cohesive development allows the consistent treatment of both problems to yield powerful new tools for the improvement of system performance Central among the themes of this work is the observation that operation of a system in feedback with a controller exposes the areas in which the model fit is constraining the controller performance achieved The book presents new techniques for the understanding of the iterative improvement of performance through the successive fitting of models using closed loop data and the design of high performance controllers using these models The subject matter includes New approaches to understanding how to affect the fit of dynamical models to physical processes through the choice of experiments data pre filtering and model structure connections between robust control design methods and their dependency on the quality of model fit experimental design in which data collected in operation under feedback can reveal areas that limit the performance achieved iterative approaches to link these model fitting and control design phases in a cogent manner so as to achieve improved performance overall The authors of individual chapters are some of the most renowned and authoritative figures in the fields of system identification and control design Iterative Identification and Control P. Albertos Pérez, Doctor Antonio Sala, 2002-05-21 An exposition of the interplay between the modelling of dynamic systems and the design of feedback controllers based on these models The authors of individual chapters are some of the most renowned and authoritative figures in the fields of system identification and control design Theory And Practice Of Control And Systems - Proceedings Of The 6th Ieee Mediterranean **Conference** Antonio Tornambe, Giuseppe Conte, Anna Maria Perdon, 1999-01-04 This volume gathers together all the lectures presented at the 6th IEEE Mediterranean Conference It focuses on the mathematical aspects in the theory and practice of control and systems including stability and stabilizability robust control adaptive control robotics and manufacturing these topics are under intense investigation and development in the engineering and mathematics communities. The volume should have immediate appeal for a large group of engineers and mathematicians who are interested in very abstract as well as very concrete aspects of control and system theory **Fuzzy Learning and Applications** Marco Russo, 2024-04-26 With low computational complexity and relatively short development time Fuzzy Logic is an indispensable tool for engineering applications The field is growing at an unprecedented rate and there is a need for a book that describes essential tools applications examples and perspectives in the field of fuzzy learning The editors of Fuzzy Learni Handbook of Research on Modern Systems Analysis and Design Technologies and Applications Syed, Mahbubur Rahman, Syed, Sharifun Nessa, 2008-07-31 This book provides a compendium of terms definitions and explanations of concepts in various areas of

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annual visit rate 1581 1000 of any age group for all sources of family planning services combined Visit rates declined sharply with age from 1447 at ages 15 24 to 479 at ages 35 44 Similar declines with age also were found in the visit rates for white and black women separately Nevertheless the annual visit rate for black women 1334 1000 was significantly higher than that for white women 1033 The highest overall visit rate was for black women 15 19 years of age 1867 1000 Nearly 2 3 of all family planning visits were to private medical sources Teenagers of all races had higher family planning service visit rates to clinics than to private medical sources as did black women age 15 24 White women age 20 and older had higher visit rates to private medical services than to clinics Never married women had higher visit rates to clinics than currently or formerly married women Data were also collected in 1982 on use of medical services for infertility by women who had difficulty in conceiving or carrying a pregnancy to term About 1 million ever married women had 1 or more infertility visits in the 12 months before the interview During the 3 years before interview about 1 9 million women had infertility visits For all ever married women as well as for white and black women separately infertility services were more likely to be secured from private medical sources than from clinics The survey design reliability of the estimates and the terms used are explained in the technical notes

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