Alfried Pollmann

LOGIC/OBJECT-ORIENTED CONCURRENT ROBOT PROGRAMMING AND PERFORMANCE ASPECTS

Logicobjectoriented Concurrent Robot Programming And Performance Aspects

Yan Bai

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7th Int. Conf. Industrial & En Frank D. Anger,Rita V. Rodriguez,Moonis Ali,1994-05-23 Over the years the promise of artificial intelligence has inspired many researchers and many schemes only to have incipient hopes thwarted by its complexity With each generation of computational engines a new wave of enthusiasm sweeps the community as solutions to a few problems come within reach However intractability and undecidability continue to frustrate the unwary practitioner while unsubstantiated methodologies offer ingenious solutions that hold more promise than potential Despite its undulate past and variegated present AI has made solid contributions to a growing information technology Expert systems and allied tools have become a mainstay of industrial and business organizations intelligent interfaces have increased accessibility of computational resources and robotic innovations have redefined the manufacturing industries Meanwhile research in evolutionary algorithms neural networks fuzzy reasoning and other exciting approaches promise continued progress in surprising new directions These proceedings record the latest results of industrial commercial military and academic artificial intelligence exploration Seventy seven papers divided into twenty different areas document a significant slice of this broad and exciting field Although dozens of themes are treated in the papers the topical divisions of this volume comprise The Software Engineering AI Interface Knowledge Based Systems Temporal Reasoning Machine Learning Robotics Intelligent Databases Planning Expert Systems Applications Search Techniques Genetic and Evolutionary Methods Design Qualitative Reasoning Neural Networks Knowledge Representation Application Paradigms Fuzzy andPattern Recognition Reasoning about Physical Systems Parallel and Distributed AI and Diagnostic Systems **American Book Publishing Record** ,1997-05 **Methodologies, Techniques, and Tools for Design Development** Murat Tanik,Atila Ertas,I. I. Esat,1994 **Software Systems in Engineering** Murat Tanik,Wilhelm Rossak,Daniel Cooke,1994 *The Cumulative Book Index* ,1997 A world list of books in the English language **An Approach to Logic, Object Oriented Concurrent Robot Programming and Performance Aspects** Alfried Pollmann,1996 **Deutsche Nationalbibliographie und Bibliographie der im Ausland erschienenen deutschsprachigen Veröffentlichungen** ,1996 **Forthcoming Books** Rose Arny,1997 Book Review Index ,1998 Every 3rd issue is a quarterly cumulation *Subject Guide to Books in Print* ,1991 **Books In Print 2004-2005** Ed Bowker Staff,Staff Bowker, Ed,2004 Whitaker's Books in Print ,1998 **Books in Print** ,1991 Verzeichnis lieferbarer Bücher ,1999 *German books in print* ,1997 Concurrent Reactive Plans Michael Beetz,2003-06-29 In this book the author presents a new computational model of forestalling common flaws in autonomous robot behavior To this end robots are equipped with structured reactive plans SRPs which are concurrent control programs that can not only be interpreted but also be reasoned about and manipulated The author

develops a representation for SRPs in which declarative statements for goals perceptions and beliefs make the structure and purpose of SRPs explicit and thereby simplify and speed up reasoning about SRPs and their projections furthermore a notation is introduced allowing for transforming and manipulating SRPs Using this notation a planning system can diagnose and forestall common flaws in robot plans that cannot be dealt with in other planning representations Finally the language for writing SRPs is extended into a high level language that can handle both planning and execution actions **Recent Advances in Robot Learning** Judy A. Franklin,Tom M. Mitchell,Sebastian Thrun,1996-06-30 Recent Advances in Robot Learning contains seven papers on robot learning written by leading researchers in the field As the selection of papers illustrates the field of robot learning is both active and diverse A variety of machine learning methods ranging from inductive logic programming to reinforcement learning is being applied to many subproblems in robot perception and control often with objectives as diverse as parameter calibration and concept formulation While no unified robot learning framework has yet emerged to cover the variety of problems and approaches described in these papers and other publications a clear set of shared issues underlies many robot learning problems Machine learning when applied to robotics is situated it is embedded into a real world system that tightly integrates perception decision making and execution Since robot learning involves decision making there is an inherent active learning issue Robotic domains are usually complex yet the expense of using actual robotic hardware often prohibits the collection of large amounts of training data Most robotic systems are real time systems Decisions must be made within critical or practical time constraints These characteristics present challenges and constraints to the learning system Since these characteristics are shared by other important real world application domains robotics is a highly attractive area for research on machine learning On the other hand machine learning is also highly attractive to robotics There is a great variety of open problems in robotics that defy a static hand coded solution Recent Advances in Robot Learning is an edited volume of peer reviewed original research comprising seven invited contributions by leading researchers This research work has also been published as a special issue of Machine Learning Volume 23 Numbers 2 and 3 *A Concurrent Real-time Autonomous Mobile Robot Programming Systems* Huiming Yu,1992

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