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12" INTERNATIONAL SYMPOSIUM ON HAPTIC INTERFACES FOR VIRTUAL ENVIRONMENT AND TELEOPERATOR SYSTEMS

HAPTICS 2004

Andrew Sears, Julie A. Jacko

10th Haptic Interfaces for Virtual Environment and Teleoperator Systems: Proceedings 2002: Orlando, FL. IEEE Symposium on Haptic Interfaces for Virtual Environment and Teleoperator Systems 2006 Computer Society Staff, 2002 Blake Hannaford, Janet M. Weisenberger, Brent Gillespie, 2006 Haptics 2003, 2003 *Haptic Interfaces for Virtual* Environment and Teleoperator Systems, 2004. HAPTICS '04. Proceedings. 12th International Symposium on IEEE Computer The Synthesis of Three Dimensional Haptic Textures: Geometry, Control, and Psychophysics Gianni Society Staff, 2004 Campion, 2011-05-16 The sense of touch is fundamental during the interaction between humans and their environment in virtual reality objects are created by computer simulations and they can be experienced through haptic devices In this context haptic textures are fundamental for a realistic haptic perception of virtual objects This book formalizes the specific artefacts corrupting the rendering of virtual haptic textures and offers a set of simple conditions to guide haptic researchers towards artefact free textures The conditions identified are also extremely valuable when designing psychophysical experiments and when analyzing the significance of the data collected The Synthesis of Three Dimensional Haptic Textures Geometry Control and Psychophysics examines the problem of rendering virtual haptic textures with force feedback devices The author provides an introduction to the topic of haptic textures that covers the basics of the physiology of the skin the psychophysics of roughness perception and the engineering challenges behind haptic textures rendering The book continues with the presentation of a novel mathematical framework that characterizes haptic devices texturing algorithms and their ability to generate realistic haptic textures Finally two psychophysical experiments link the perception of roughness with the parameters of the haptic rendering algorithms This book formalizes the specific artefacts corrupting the rendering of virtual haptic textures and offers a set of simple conditions to guide haptic researchers towards artefact free textures The conditions identified are also extremely valuable when designing psychophysical experiments and when analyzing the significance of the HAPTICS 2004 .2004 data collected Haptic Interfaces for Accessibility, Health, and Enhanced Quality of Life Troy McDaniel, Sethuraman Panchanathan, 2019-12-18 This book is the first resource to provide in depth coverage on topical areas of assistive rehabilitative and health related applications for haptic touch based technologies Application topics are grouped into thematic areas spanning haptic devices for sensory impairments health and well being and physical impairments which are illustrated in this book A diverse group of experts in the field were invited to contribute different chapters to provide complementary and multidisciplinary perspectives Unlike other books on haptics which focus on human haptic perception specific modalities of haptics e g realistic haptic rendering or broadly cover the subfields of haptics this book takes an application oriented approach to present a tour of how the field of haptics has been advanced with respect to important impactful thematic focuses Under Theme 1 Sensory Impairments haptics technologies to support individuals with sensory impairments is presented which includes Spatial awareness in sensory impairments through touch Haptically

assisted interfaces for persons with visual impairments and Enabling learning experiences for visually impaired children by interaction design Under Theme 2 Haptics for Health and Well Being haptics technologies aimed at supporting exercise and healthy aging will be covered including Haptics in rehabilitation exergames and health Therapeutic haptics for mental health and well being and Applications of haptics in medicine Under Theme 3 Haptics for Physical Impairments haptics technologies for enhancing the quality of life for individuals with weakened impaired limbs or neurological diseases impacting movement is targeted including Assistive soft exoskeletons with pneumatic artificial muscles Haptics for accessibility in rehabilitative hardware and intelligent robotics and immersive displays for enhancing haptic interaction in physical rehabilitation environments Engineers scientists and researchers working in the areas of haptics multimedia virtual augmented mixed reality human computer interaction assistive technologies rehabilitative technologies healthcare technologies and or actuator design will want to purchase this book Advanced level students and hobbyists interested in haptics will also be interested in this book Haptic Interaction Hiroyuki Kajimoto, Dongjun Lee, Sang-Youn Kim, Masashi Konyo, Ki-Uk Kyung, 2019-05-13 This book constitutes the proceedings of the third international conference AsiaHaptics 2018 held in Songdo Korea It presents the state of the art of the diverse haptics touch related research including perception and illusion development of haptics devices and applications to a wide variety of fields such as education medicine telecommunication navigation and entertainment This book is a valuable resource not only for active haptics researchers but also for general readers wishing to understand the status quo in this interdisciplinary area of science and technology Haptic Rendering for Simulation of Fine Manipulation Dangxiao Wang, Jing Xiao, Yuru Zhang, 2014-10-17 This book introduces the latest progress in six degrees of freedom 6 DoF haptic rendering with the focus on a new approach for simulating force torque feedback in performing tasks that require dexterous manipulation skills One of the major challenges in 6 DoF haptic rendering is to resolve the conflict between high speed and high fidelity requirements especially in simulating a tool interacting with both rigid and deformable objects in a narrow space and with fine features The book presents a configuration based optimization approach to tackle this challenge Addressing a key issue in many VR based simulation systems the book will be of particular interest to researchers and professionals in the areas of surgical simulation rehabilitation virtual assembly and inspection and maintenance **End-User** Computing: Concepts, Methodologies, Tools, and Applications Clarke, Steve, 2008-02-28 Covers the important concepts methodologies technologies applications social issues and emerging trends in this field Provides researchers managers and other professionals with the knowledge and tools they need to properly understand the role of end user computing in the Human Computer Interaction: Concepts, Methodologies, Tools, and Applications Ang, Chee modern organization Siang, Zaphiris, Panayiotis, 2008-10-31 Penetrates the human computer interaction HCI field with breadth and depth of Advances in Haptics Mehrdad Hosseini Zadeh, 2010-04-01 Haptic interfaces are divided into two comprehensive research main categories force feedback and tactile Force feedback interfaces are used to explore and modify remote virtual objects in

three physical dimensions in applications including computer aided design computer assisted surgery and computer aided assembly Tactile interfaces deal with surface properties such as roughness smoothness and temperature Haptic research is intrinsically multi disciplinary incorporating computer science engineering control robotics psychophysics and human motor control By extending the scope of research in haptics advances can be achieved in existing applications such as computer aided design CAD tele surgery rehabilitation scientific visualization robot assisted surgery authentication and graphical user interfaces GUI to name a few Advances in Haptics presents a number of recent contributions to the field of haptics Authors from around the world present the results of their research on various issues in the field of haptics Paul M. Frank, 2012-12-06 Advances in Control contains keynote contributions and tutorial material from the fifth European Control Conference held in Germany in September 1999 The topics covered are of particular relevance to all academics and practitioners in the field of modern control engineering These include Modern Control Theory Fault Tolerant Control Systems Linear Descriptor Systems Generic Robust Control Design Verification of Hybrid Systems New Industrial Perspectives Nonlinear System Identification Multi Modal Telepresence Systems Advanced Strategies for Process Control Nonlinear Predictive Control Logic Controllers of Continuous Plants Two dimensional Linear Systems This important collection of work is introduced by Professor P M Frank who has almost forty years of experience in the field of automatic control State of the art research expert opinions and future developments in control theory and its industrial applications combine to make this an essential volume for all those involved in control engineering The Human-Computer Interaction Handbook Andrew Sears, Julie A. Jacko, 2007-09-19 This second edition of The Human Computer Interaction Handbook provides an updated comprehensive overview of the most important research in the field including insights that are directly applicable throughout the process of developing effective interactive information technologies It features cutting edge advances to the scientific

Human-Computer Interaction Fundamentals Andrew Sears, Julie A. Jacko, 2009-03-02 Hailed on first publication as a compendium of foundational principles and cutting edge research The Human Computer Interaction Handbook has become the gold standard reference in this field Derived from select chapters of this groundbreaking and authoritative resource Human Computer Interaction Fundamentals emphasizes emerging topics such as sen **Rehabilitation Robotics** Sashi S. Kommu, 2007-08-01 The coupling of several areas of the medical field with recent advances in robotic systems has seen a paradigm shift in our approach to selected sectors of medical care especially over the last decade Rehabilitation medicine is one such area The development of advanced robotic systems has ushered with it an exponential number of trials and experiments aimed at optimising restoration of quality of life to those who are physically debilitated Despite these developments there remains a paucity in the presentation of these advances in the form of a comprehensive tool This book was written to present the most recent advances in rehabilitation robotics known to date from the perspective of some of the leading experts in the field and presents an interesting array of developments put into 33 comprehensive chapters The

chapters are presented in a way that the reader will get a seamless impression of the current concepts of optimal modes of both experimental and ap plicable roles of robotic devices **The Power of Touch** Elizabeth Pye,2016-09-16 Despite the fact that we have a range of senses with which to perceive the world around us museums and other cultural institutions have traditionally used sight as the main way to convey information In everyday life though we use touch constantly in conjunction with sight Why then does it play so small a role in the study and enjoyment of museum objects Contributors to this volume explore how the sense of touch can be utilized in cultural institutions to facilitate understanding and learning

Multisensory Softness Massimiliano Di Luca, 2014-07-23 Offers a unique multidisciplinary overview of how humans interact with soft objects and how multiple sensory signals are used to perceive material properties with an emphasis on object deformability The authors describe a range of setups that have been employed to study and exploit sensory signals involved in interactions with compliant objects as well as techniques to simulate and modulate softness including a psychophysical perspective of the field Multisensory Softness focuses on the cognitive mechanisms underlying the use of multiple sources of information in softness perception Divided into three sections the first Perceptual Softness deals with the sensory components and computational requirements of softness perception the second Sensorimotor Softness looks at the motor components of the interaction with soft objects and the final part Artificial Softness focuses on the identification of exploitable guidelines to help replicate softness in artificial environments Enabling 5G Communication Systems to Support Vertical Industries Muhammad Ali Imran, Yusuf Abdulrahman Sambo, Qammer H. Abbasi, 2019-08-19 How 5G technology can support the demands of multiple vertical industries Recent advances in technologyhave created new vertical industries that are highly dependent on the availability and reliability of data between multiple locations The 5G system unlike previous generations will be entirely data driven addressing latency resilience connection density coverage area and other vertical industry criteria Enabling 5G Communication Systems to Support Vertical Industries demonstrates how 5G communication systems can meet the needs unique to vertical industries for efficient cost effective delivery of service Covering both theory and practice this book explores solutions to problems in specific industrial sectors including smart transportation smart agriculture smart grid environmental monitoring and disaster management The 5G communication system will have to provide customized solutions to accommodate each vertical industry s specific requirements Whether an industry practitioner designing the next generation of wireless communications or a researcher needing to identify open issues and classify their research this timely book Covers the much discussed topics of supporting multiple vertical industries and new ICT challenges Addresses emerging issues and real world problems surrounding 5G technology in wireless communication and networking Explores a comprehensive array of essential topics such as connected health smart transport smart manufacturing and more Presents important topics in a clear concise style suitable for new learners and professionals alike Includes contributions from experts and industry leaders system diagrams charts tables and examples Enabling 5G

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Haptic Guidance for Extended Range Telepresence Antonia Pérez Arias, 2014-05-22 A novel navigation assistance for extended range telepresence is presented The haptic information from the target environment is augmented with guidance commands to assist the user in reaching desired goals in the arbitrarily large target environment from the spatially restricted user environment Furthermore a semi mobile haptic interface was developed one whose lightweight design and setup configuration atop the user provide for an absolutely safe operation and high force display quality

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