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Bruce R. Donald

Error Detection and Recovery in Robotics



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Error Detection And Recovery In Robotics

Maria Gini

Error Detection And Recovery In Robotics:

Error Detection and Recovery in Robotics Bruce R. Donald,1987 Error Detection and Recovery for Robot Motion Planning with Uncertainty Bruce Randall Donald,MASSACHUSETTS INST OF TECH CAMBRIDGE ARTIFICIAL INTELLIGENCE LAB.,Massachusetts Institute of Technology. Artificial Intelligence Laboratory,1987 Robots must plan and execute tasks in the presence of uncertainty Uncertainty arises from sensing errors controls errors and uncertainty in the geometry of the environment The last which is called model error has received little previous attention This document presents a framework for computing motion strategies that are guaranteed to succeed in the presence of all three kinds of uncertainty The motion strategies comprise sensor based gross motions complaint motions and simple pushing motions It is not always possible to find plans that are guaranteed to succeed For example if tolerancing errors render an assembly infeasible the plan executor should stop and signal failure In such cases the insistence on guaranteed success is to restrictive For this reason Error Detection and Recovery EDR strategies there is no possibility that the plan will fail without the executor realizing it The EDR framework fills a gap when guaranteed plans cannot be found or do not exist it provides a technology for constructing plans that might work but fail in a reasonable way when they cannot Keywords Robotics Mobility

Robotics John Baillieul,1990 Contains the six lectures of an AMS short course in robotics in Louisville Kentucky January 1990 some mathematical aspects of robotics manipulator kinematics the resolution of kinematic redundancy grasping and manipulation using multifingered robot hands planning and executing robot assembly Algorithms for Robotic Motion and Manipulation Jean-Paul Laumond,Mark Overmars,1997-02-11 This volume deals with core problems in robotics like motion planning sensor based planning manipulation and assembly planning It also discusses the application of robotics algorithms in other domains such as molecular modeling computer graphics and image analysis Topics Include Planning Sensor Based Motion Planning Control and Moti Library of Congress Subject Headings Library of Congress, 2007

Robot Motion Planning Jean-Claude Latombe, 2012-12-06 One of the ultimate goals in Robotics is to create autonomous robots Such robots will accept high level descriptions of tasks and will execute them without further human intervention The input descriptions will specify what the user wants done rather than how to do it The robots will be any kind of versatile mechanical device equipped with actuators and sensors under the control of a computing system Making progress toward autonomous robots is of major practical inter est in a wide variety of application domains including manufacturing construction waste management space exploration undersea work as sistance for the disabled and medical surgery It is also of great technical interest especially for Computer Science because it raises challenging and rich computational issues from which new concepts of broad useful ness are likely to emerge Developing the technologies necessary for autonomous robots is a formidable undertaking with deep interweaved ramifications in auto mated reasoning perception and control It raises many important prob lems One of them motion planning is the central theme of this book It can be loosely stated as follows

How can a robot decide what motions to perform in order to achieve goal arrangements of physical objects This capability is eminently necessary since by definition a robot accomplishes tasks by moving in the real world The minimum one would expect from an autonomous robot is the ability to plan its x Preface own motions **Library of Congress Subject Headings** Library of Congress. Cataloging Policy and Support Office, 2009 Library of Congress Subject Headings Library of Congress. Office for Subject Cataloging Policy, 1991 Planning Algorithms Steven M. LaValle, 2006-05-29 Planning algorithms are impacting technical disciplines and industries around the world including robotics computer aided design manufacturing computer graphics aerospace applications drug design and protein folding This coherent and comprehensive book unifies material from several sources including robotics control theory artificial intelligence and algorithms The treatment is centered on robot motion planning but integrates material on planning in discrete spaces A major part of the book is devoted to planning under uncertainty including decision theory Markov decision processes and information spaces which are the configuration spaces of all sensor based planning problems. The last part of the book delves into planning under differential constraints that arise when automating the motions of virtually any mechanical system This text and reference is intended for students engineers and researchers in robotics artificial intelligence and control theory as well as computer graphics algorithms and computational biology **Expert Systems and Robotics** Timothy Jordanides, Bruce Torby, 2012-12-06 The areas of intelligent machines or robotic systems is of enormous technological and economic interest as competition in productivity intensifies This volume gives the proceedings of the 1990 Advanced Study Institute on Expert Systems and Robotics It presents research work already accomplished in the analytical theory of intelligent machines work in progress and of current interest and some specific examples for further research. The papers in the volume range from the most theoretical to some descriptions of very practical working robots. The papers are organized into sections on vision and image analysis robotic sensory systems software hardware and system simulation robot control applications and reports of Artificial Immune Systems Pietro Lio, Giuseppe Nicosia, Thomas Stibor, 2011-07-06 This book constitutes group meetings the refereed proceedings of the 10th International Conference on Artificial Immune Systems ICARIS 2011 held in Cambridge UK in July 2011 The 37 revised full papers were carefully reviewed and selected from numerous submissions The papers are organized in topical sections on immunoinformatics and computational immunology theory of immunological computation and applied immunological computation Systems Collaboration and Integration Chin-Yin Huang, Sang Won Yoon, 2023-10-17 This book is a groundbreaking exploration of the historical and contemporary challenges in systems collaboration and integration This exceptional book delves into engineering design planning control and management offering invaluable insights into the evolving nature of systems and networks In an era defined by the ongoing cyber and digital transformation coupled with artificial intelligence and machine learning this book offers insights into the future of systems collaboration and integration Over the past three decades the PRISM Center and its affiliated PRISM Global

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