HIERARCHICALLY INTELLIGENT MACHINES

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George N Saridis

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Hierarchically Intelligent Machines

Spyros G. Tzafestas

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engineering systems science computer science and management science Currently the majority of working systems in practice are of the semi autonomous type needing some level of human intervention Therefore much effort is presently devoted in academic research and industrial environments towards further increasing the level of autonomy This book provides a collection of essays which cover the latest research in the IAS field and present a rich set of results accompanied by detailed descriptions of the relevant concepts tools techniques and hardware software designs The book contains twenty three chapters grouped in the following parts Part 1 General concepts architectures and technologies Part 2 Mobile walking and snake like robots Part 3 Applications PART 1 involves the first seven chapters which deal with generic issues Chapter 1 by S G Tzafestas provides some background material accompanied by a description of two research IAS prototypes namely a car disassembly robotic system and a semi autonomous autonomous robotic wheelchair Chapter 2 by G Bolmsjo M Olsson and K Brink presents a generic event based control system structure for the control of a robotic workcell including its implementation where the autonomous operation is achieved via reactive replanning and configurable corrections

Robotics: From Manipulator To Mobilebot Zixing Cai, 2022-08-29 This book is a comprehensive collection and practical guide on robotics derived from the author's research in robotics since 1988 The Chinese edition of this book has sold over 300 000 copies and is one of the best selling books on robotics in China The book covers the core technology of robotics including the basic theories and techniques of robot manipulator mobile robots to focus on location navigation and intelligent control underpinned by artificial intelligence and deep learning Several case studies from national research projects in China are also included to help readers understand the theoretical foundations of robotics and related application developments This book is a valuable reference for undergraduate and graduate students of robotics courses **Intelligent Robotic Systems** Spyros G. Tzafestas, 2020-08-27 A multiplicity of techniques and angles of attack are incorporated in 18 contributions describing recent developments in the structure architecture programming control and implementation of industrial robots capable of performing intelligent action and decision making Annotation copyright Book Intelligent Robotic Systems: Theory, Design and Applications Kimon P. Valavanis, George N. Saridis, 2012-12-06 Since the late 1960s there has been a revolution in robots and industrial automation from the design of robots with no computing or sensorycapabilities first generation to the design of robots with limited computational power and feedback capabilities second generation and the design of intelligent robots third generation which possess diverse sensing and decision making capabilities The development of the theory of intelligent machines has been developed in parallel to the advances in robot design This theory is the natural outcome of research and development in classical control 1950s adaptive and learning control 1960s self organizing control 1970s and intelligent control systems 1980s The theory of intelligent machines involves utilization and integration of concepts and ideas from the diverse disciplines of science engineering and mathematics and fields like artificial intelligence system theory and operations research The main focus and motivation is to bridge the gap

between diverse disciplines involved and bring under a common cover several generic methodologies pertaining to what has been defined as machine intelligence Intelligent robotic systems are a specific application of intelligent machines They are complex computer controlled robotic systems equipped with a diverse set of visual and non visual sensors and possess decision making and problem solving capabilities within their domain of operation Their modeling and control is accomplished via analytical and heuristic methodologies and techniques pertaining to generalized system theory and artificial intelligence Intelligent Robotic Systems Theory Design and Applications presents and justifies the fundamental concepts and ideas associated with the modeling and analysis of intelligent robotic systems Appropriate for researchers and engineers in the general area of robotics and automation Intelligent Robotic Systems is both a solid reference as well as a text for a graduate level course in intelligent robotics machines Machine Intelligence and Knowledge Engineering for Robotic Applications Andrew K.C. Wong, Alan Pugh, 2012-12-06 This book is the outcome of the NATO Advanced Research Workshop on Machine Intelligence and Knowledge Engineering for Robotic Applications held at Maratea Italy in May 1986 Attendance of the workshop was by invitation only Most of the participants and speakers are recognized leaders in the field representing industry government and academic community worldwide The focus of the workshop was to review the recent advances of machine intelligence and knowledge engineering for robotic appli cations It covers five main areas of interest They are grouped into five sections 1 Robot Vision 2 Knowledge Representation and Image Understanding 3 Robot Control and Inference Systems 4 Task Planning and Expert Systems 5 Software Hardware Systems Also included in this book are a paper from the Poster Session and a brief report of the panel discussion on the Future Direction in Knowledge Based Robotics Section I of this book consists of four papers It begins with a review of the basic concepts of computer vision with emphasis on techniques specific for robot vision systems. The next paper pre sents a comprehensive 3 D vision system for Reliable Plan Selection By Intelligent Machines John E McInroy, Joseph C Musto, George N robotic application Saridis, 1996-02-29 This book derives techniques which allow reliable plans to be automatically selected by Intelligent Machines It concentrates on the uncertainty analysis of candidate plans so that a highly reliable candidate may be identified and used For robotic components such as a particular vision algorithm for pose estimation or a joint controller methods are explained for directly calculating the reliability However these methods become excessively complex when several components are used together to complete a plan Consequently entropy minimization techniques are used to estimate which complex tasks will perform reliably The book first develops tools for directly calculating the reliability of sub systems and methods of using entropy minimization to greatly facilitate the analysis are explained Since these sub systems are used together to accomplish complex tasks the book then explains how complex tasks can be efficiently evaluated Distributed Intelligence Systems D. Mladenov, 1989 Hardbound This volume focuses on the recent advances in distributed intelligent control systems Topics covered include applications and case studies of distributed control systems design methodologies for distributed intelligent systems and architectural considerations of computer design for this type of control system Containing 54 papers the Proceedings will be a useful reference source for all those involved in the designing and implementing of distributed control systems

Measuring the Performance and Intelligence of Systems Alex Meystel, E. R. Messina, 2001

Advanced Robotics & Intelligent Machines J. O. Gray, Darwin G. Caldwell, 1996 Advanced robotics describes the use of sensor based robotic devices which exploit powerful computers to achieve the high levels of functionality that begin to mimic intelligent human behaviour The object of this book is to summarise developments in the base technologies survey recent applications and highlight new advanced concepts which will influence future progress **Designing Intelligent Machines Volume 1** George Rzevski, 2014-06-28 Mechatronics is the fusion of mechanics and electronics in the design of intelligent machines Such machines now play an important role in consumer products transport systems manufacturing and the service sector This book sets out the fundamentals of mechatronics and the engineering concepts and techniques that underpin the subject planning search techniques sensors actuators control systems and architectures This student guide discusses the building blocks of mechatronic systems in terms of the subsystems for perception cognition and execution as a framework for designing intelligent machines such as video cameras robots and **Progress in Evolutionary Computation** Xin Yao, 1995-08-10 This volume contains the best automatic guided vehicles carefully revised full papers selected from the presentations accepted for the AI 93 and AI 94 Workshop on Evolutionary Computation held in Australia The 21 papers included cover a wide range of topics in the field of evolutionary computation from constrained function optimization to combinatorial optimization from evolutionary programming to genetic programming from robotic strategy learning to co evolutionary game strategy learning. The papers reflect important recent progress in the field more than half of the papers come from overseas **Intelligent Control** Zi-Xing Cai, 1997 Introducton Methology of knowledge representation General inference principles Hierarchical control systems Expert control systems Fuzzy control systems Neurocontrol systems Learning control systems Intelligente control systems in application Prospectives of intelligente control References Bibliography Subject index **On Intelligence** Jeff Hawkins, Sandra Blakeslee, 2024-09-04 The inventor of the PalmPilot shares a compelling new theory of intelligence brain function and the future of artificial intelligence Tech innovator Jeff Hawkins reshaped our relationship to computers with devices like the PalmPilot Now he stands ready to revolutionize both neuroscience and computing in one stroke with a new understanding of intelligence itself In this book Hawkins develops a powerful theory of human cognition and explains how based on his theory we can finally build intelligent machines According to Hawkins the brain is a complex system that remembers sequences of events and their nested relationships This style of organization reflects the true structure of the world and allows us to make increasingly accurate predictions This memory prediction process in turn forms the basis of intelligence perception creativity and even consciousness In an engaging style accessible to the general reader Hawkins shows how a clear understanding of

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Hierarchically Intelligent Machines Introduction

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