

Example 2. A cam mechanism is shown in Fig. 5.28. It is desired to determine the acceleration of the reciprocating follower 4. The path that P_4 traces on 2 is shown. The velocity polygon is shown in Fig. 5.29 and the acceleration polygon in Fig. 5.30. The acceleration of P_4 is

$$A_{P_4} = A_{P_2}^0 + A_{P_1}^1 + A_{P_3/P_2}^2 + A_{P_4/P_3}^3 + 2V_{P_3/P_2}\omega_{P_2}$$

The components are

$$A_{P_2}^0 = 60\pi a_{P_2}^0 = \frac{1.72}{12} (15)^2 = 32.2 \text{ ipd}^2$$

The cam has no angular acceleration; therefore

$$A_{P_1}^1 = 0$$

$$A_{P_3/P_2}^2 = \frac{V_{P_3/P_2}^2}{R} = \frac{V_{P_3/P_2}^2}{a} = 0$$

where R is the radius of curvature of the path of P_3 on 2 at the point of contact.

$$2V_{P_3/P_2}\omega_{P_2} = (2)(2.5)(15) = 75 \text{ ipd}^2$$

These two vectors are laid off starting from a' . The direction of A_{P_3/P_2}^2 is tangent to the path that P_3 traces on 2. A line in this direction through the terminus of

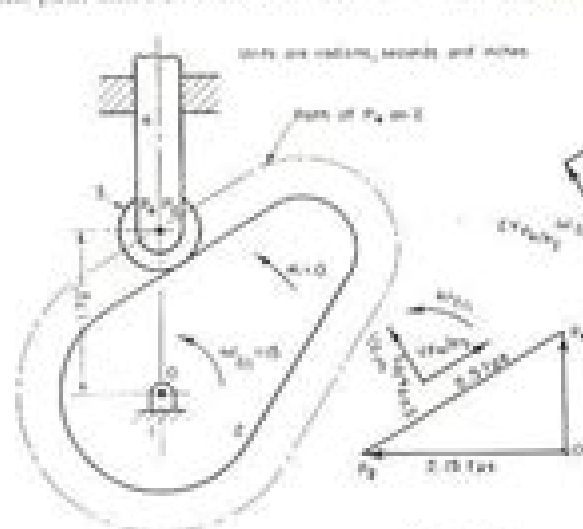


Fig. 5.28

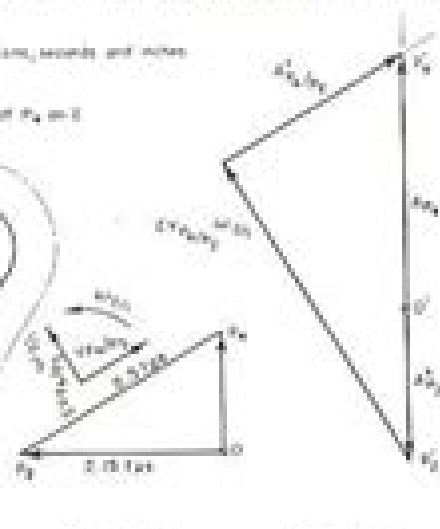


Fig. 5.29



Fig. 5.30

$2V_{P_3/P_2}\omega_{P_2}$ contains P_4' . The acceleration of P_4 relative to the frame is along the centerline of the follower. A line in this direction through a' contains P_4'' and P_4' is located at the intersection of these two lines. On the drawing A_{P_4} scales 51.8 ipd².

Example 3. A quick-return mechanism is shown in Fig. 5.31. Member 2 has constant angular velocity as shown. The angular acceleration of link 3 is desired. The acceleration of P_4 must be determined first. The equation is

$$A_{P_4} = A_{P_2}^0 + A_{P_1}^1 + A_{P_3/P_2}^2 + A_{P_4/P_3}^3 + 2V_{P_3/P_2}\omega_{P_2}$$

In order to solve this equation it is necessary to know the radius of curvature on the path that P_3 traces on 2. This is not known. The path that P_3 traces on 2 is a straight line along the link. This path can be used if the equation is written as though solving for the acceleration of P_3 .

$$A_{P_3} = A_{P_2}^0 + A_{P_1}^1 + A_{P_3/P_2}^2 + A_{P_4/P_3}^3 + 2V_{P_4/P_3}\omega_{P_3}$$

The vectors that can be calculated are

$$A_{P_2}^0 = P_2\omega_{P_2}^2 = \frac{6}{12} (20)^2 = 200 \text{ ipd}^2$$

$$A_{P_1}^1 = \frac{V_{P_1}^2}{P_1P_2} = \frac{(3)^2}{12} = 30 \text{ ipd}^2$$

$$A_{P_3/P_2}^2 = 0$$

$$\omega_{P_3} = \frac{V_{P_3/P_2}}{P_3P_2} = \frac{5}{12} = 5 \text{ radians per sec}$$

$$2V_{P_4/P_3}\omega_{P_3} = (2)(8.55)(5) = 100 \text{ ipd}^2$$

The directions of A_{P_3/P_2}^2 and A_{P_4/P_3}^3 are known. This information is sufficient for completing the polygon. One arrangement is shown in Fig. 5.31. The known

paths are return, smooth and rapid.



Fig. 5.31

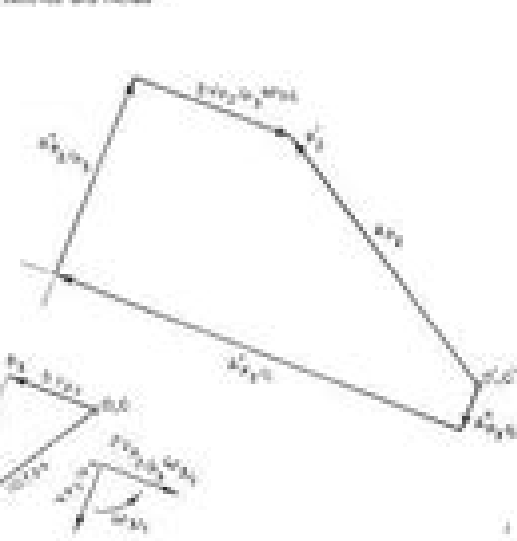


Fig. 5.32

Fig. 5.33

vectors $A_{P_2}^0$, $A_{P_1}^1$, and $2V_{P_4/P_3}\omega_{P_3}$ are laid off as shown. Lines in the known directions of the other two vectors complete the polygon. Then A_{P_4} scales 275 ipd².

$$\omega_{P_3} = \frac{A_{P_3/P_2}^2}{P_3P_2} = \frac{275}{12} = 220 \text{ radians per sec}$$

5.9. Complex mechanisms. In Chapter 4 it was found that some mechanisms require trial solutions in the construction of velocity poly-

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Burkett, Brendan



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Kinematics of Machines Leon Marr Sahag, 1952 *Kinematics of Machinery* John Henry Barr, 1899 A collection of critical essays on Proust's Remembrance of Things Past arranged in chronological order of publication **Spatial Mechanisms** Antonio Lopez-Gomez, 2001-05-04 Spatial Mechanisms Analysis and Synthesis comprises the study of the three dimensional relative motion between the components of a machine Each chapter in this book presents a concise but thorough fundamental statement of the theory principles and methods It then follows this with a selected number of worked examples Numerous references provided at the end of chapters and the bibliography at the end of the book serve as helpful sources for further study *The Machines of Leonardo Da Vinci and Franz Reuleaux* Francis C. Moon, 2007-05-30 This fascinating book will be of as much interest to engineers as to art historians examining as it does the evolution of machine design methodology from the Renaissance to the Age of Machines in the 19th century It provides detailed analysis comparing design concepts of engineers of the 15th century Renaissance and the 19th century age of machines from a workshop tradition to the rational scientific discipline used today **Machine Design: Kinematics of machinery.-pt. 2. Form, strength, and proportions of parts** Forrest Robert Jones, 1897 **SSC Junior Engineer Mechanical Recruitment Exam Guide 4th Edition** Er. Deepak Pathak, 2018-12-17 SSC Junior Engineer Mechanical Engineering Recruitment Exam Guide 3rd Edition is a comprehensive book for those who aspire to excel in SSC Paper 1 and Paper 2 for Jr Engineer Mechanical post The book now comes with the thoroughly revised updated Technical section The book now contains 2016 2015 2014 Solved Papers The book has been divided into three sections namely Mechanical Engineering General Intelligence Reasoning and General Awareness each subdivided into ample number of solved problems designed on the lines of questions asked in the exam All the chapters contain detailed theory along with solved examples Exhaustive question bank at the end of each chapter is provided in the form of Exercise Solutions to the Exercise have been provided at the end of each chapter Solved Question paper of Another unique feature of the book is the division of its General Awareness section into separate chapters on History Geography Polity Economy General Science Miscellaneous topics and Current Affairs **Engineering and Metallurgical Books, 1907-1911** Robert Alexander Peddie, 1912 *Classical and Modern Approaches in the Theory of Mechanisms* Nicolae Pandrea, Dinel Popa, Nicolae-Doru Stanescu, 2017-02-14 Classical and Modern Approaches in the Theory of Mechanisms is a study of mechanisms in the broadest sense covering the theoretical background of mechanisms their structures and components the planar and spatial analysis of mechanisms motion transmission and technical approaches to kinematics mechanical systems and machine dynamics In addition to classical approaches the book presents two new methods the analytic assisted method using Turbo Pascal calculation programs and the graphic assisted method outlining the steps required for the development of graphic constructions using AutoCAD the applications of these methods are illustrated with examples Aimed at students of mechanical engineering and engineers designing and developing mechanisms in their

own fields this book provides a useful overview of classical theories and modern approaches to the practical and creative application of mechanisms in seeking solutions to increasingly complex problems *Theory of Machines & Mechanisms* G. C. Mohan Kumar, 2025-06-01 **International Symposium on History of Machines and Mechanisms Proceedings**

HMM 2000 Marco Ceccarelli, 2013-11-11 The International Symposium on History of Machines and Mechanisms is a new initiative to promote explicitly researches and publications in the field of the History of TMM Theory of Machines and Mechanisms It was held at the University of Cassino Italy from 11 to 13 May 2000 The Symposium was devoted mainly to the technical aspects of historical developments and therefore it has been addressed mainly to the IFToMM Community In fact most the authors of the contributed papers are experts in TMM and related topics This has been indeed a challenge convincing technical experts to go further in depth into the background of their topics of expertise We have received a very positive response as can be seen by the fact that these Proceedings contain contributions by authors from all around the world We received about 50 papers and after review about 40 papers were accepted for both presentation and publishing in the Proceedings This means also that the History of TMM is of interest everywhere and indeed an in depth knowledge of the past can be of great help in working on the present and in shaping the future with new ideas I believe that a reader will take advantage of the papers in these Proceedings with further satisfaction and motivation for her or his work historical or not These papers cover the wide field of the History of Mechanical Engineering and particularly the History of TMM Applied Sport Mechanics 4th Edition Burkett, Brendan, 2019 Applied Sport Mechanics Fourth Edition helps undergraduates understand how the fundamental laws of human movement affect athletes performances Foundational principles of kinetics kinematics and sports technique are clearly presented and then explored through a variety of applied scenarios

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and identification and description and evaluation **Management of Thyroid Disorders** Mr. Rohit Manglik, 2024-07-30
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against the background of the industrial revolution the theory of machines and thus the kinematics of mechanisms received a great deal of attention In the final analysis this led to the birth of the discipline *Transactions* Institution of Engineers and Shipbuilders in Scotland,1898 **Calendar** University of British Columbia,1949 *Applied Kinematics* Kurt Hain,1967

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