



# Interactive Systems For Experimental Mat

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## **Interactive Systems For Experimental Mat:**

Sensor-Actuator Supported Implicit Interaction in Driver Assistance Systems Andreas Riener, 2011-06-07 Andreas Riener studies the influence of implicit interaction using vibro tactile actuators as additional sensory channels for car driver feedback and pressure sensor arrays for implicit information transmission from the driver toward the vehicle The results of his experiments suggest the use of both vibro tactile notifications and pressure sensor images to improve vehicle handling performance and to decrease the driver's cognitive workload

*Designing Human-Swarm Interaction Systems* Oscar Bjurling, 2025-02-20 Swarms of Unmanned Aerial Vehicles UAVs or drones are envisioned to transform various fields from emergency response to law enforcement and military operations Drone swarms provide scalable adaptable and decentralized solutions for dynamic work environments However the successful integration of these multi agent systems into real world settings presents significant challenges particularly in terms of how humans can safely and effectively interact with and control these systems Human Swarm Interaction HSI aims to address these challenges by exploring how human operators can manage multiple drones in a cohesive manner even under highly complex uncertain conditions This thesis studies the problem of designing effective interaction mechanisms and interfaces for human operators to command drone swarms specifically addressing challenges such as managing a large number of drones supporting operators situational awareness and balancing between centralized and decentralized control The research highlights the necessity of rethinking conventional approaches by introducing alternative conceptual models such as the choir metaphor which reimagines drone swarms as coordinated semi centralized ensembles rather than purely emergent decentralized collectives This metaphor aims to balance the collective often unpredictable behavior of drone swarms with the predictable directed actions needed in operational environments By demonstrating how this metaphor can be operationalized in an HSI system architecture the thesis provides new avenues for conceptualizing human interaction with autonomous systems Using a design research approach incorporating multiple case study and scenario based design activities to envision future swarm application in dialogue with prospective end users the thesis develops and evaluates prototypes that embody these nuanced HSI concepts The interface prototypes draw design inspiration from Real Time Strategy RTS games These elements include group commands high level mission planning and resource pooling to create a hybrid interaction model that allows operators to maintain both a broad overview and precise control of multiple autonomous and collaborating drones Domain expert evaluations of these prototypes in contexts such as firefighting and airport management validate the practical utility of these concepts The findings emphasize the value of adopting a Human Technology Organization HTO perspective in the design of HSI systems Rather than focusing solely on the interaction between humans and technology this systems thinking approach acknowledges that drone swarms must be integrated into larger organizational frameworks such as emergency response command structures or airport ground operations teams It demonstrates that successful deployment requires accounting for

the broader organizational context including roles workflows and coordination needs This holistic approach to HSI system design ensures that drone swarms not only meet technical performance criteria such as reliability responsiveness and scalability but also align with human and organizational needs facilitating their adoption and effective use in a wide range of real world scenarios Ultimately these contributions are intended to bridge the gap between theoretical models of swarm control and practical deployment advancing both the field of HSI and the broader adoption of drone swarm technologies

Sv rmar av obemannade luftfarkoster UAV eller dr nare f rv ntas omvandla flera omr den exempelvis r ddningsinsatser brottsbek mpning och milit roperationer Dr narsv rmar innebar skalbara anpassningsbara och decentraliserade l sningar for dynamiska arbetsuppgifter Den lyckade integreringen av dessa multi agent system i verkliga milj er innebar dock betydande utmaningar s rskilt med avseende p hur m nniskor s kert och effektivt interagerar med och kontrollerar dessa system Forskningsf llet M nniska Sv rm Interaktion MSI syftar till att m ta dessa utmaningar genom att unders ka hur m nskliga operatorer kan hantera flera dr nare p ett sammanh ngande vis ven under komplexa och os kra f rh llanden Denna avhandling utreder problemet att utforma effektiva och s kra interaktionsmekanismer och gr nssnitt for m nskliga operatorer att leda dr narsv rmar specifikt genom att adressera utmaningar som att hantera ett stort antal dr nare st dja operatorers situationsmedvetenhet och balansera mellan centraliserad och decentraliserad kontroll Avhandlingen betonar vikten av att ifr gasatta konventionella tillv gag ngss tt genom att introducera alternativa konceptuella modeller s som k r metaforen som omtolkar dr narsv rmar som koordinerade semicentraliserade ensembler snarare n rent decentraliserade kollektiv Denna metafor syftar till att balansera det kollektiva ofta of ruts gbara beteendet hos dr narsv rmar med de f ruts gbara riktade handlingar som beh vs i operativa milj er Genom att visa hur denna metafor kan operationaliseras i en MSI systemarkitektur erbjuder avhandlingen nya s tt att konceptualisera m nsklig interaktion med autonoma system Genom att till mpa en designforskningsmetod som innefattar fallstudier och scenariobaserade designaktiviteter f r att f rest lla sig framtida sv rmtill mpningar i dialog med potentiella slutanv ndare utvecklar och utv rderar avhandlingen prototyper som manifesterar dessa nyanserade MSI koncept Gr nssnittens prototyper drar designinspiration fr n realtidsstrategispel RTS Dessa element inkluderar enhetshantering och kommandon p gruppniv strategisk uppdragsplanering och resursdelning f r att skapa en hybrid interaktionsmodell som g r det m jligt f r operat rer att b de bibeh lla en bred l gesbild och ut va precis kontroll ver flera autonoma och samverkande dr nare Dom nexperters utv rderingar av dessa prototyper i arbetskontexter som brandbek mpning och flygplatsledning p visar den praktiska anv ndbarheten av dessa koncept Resultaten betonar v rdet av att anta ett M nniska Teknik Organisation MTO perspektiv vid utformningen av MSI system Snarare n att enbart fokusera p interaktionen mellan m nniskor och teknik erk nner detta systemt nkande tillv gag ngss tt att dr narsv rmar m ste integreras i st rre organisatoriska ramar s som ledningsstrukturer for r ddningsinsatser eller markoperativa team p flygplatser Det visar att framg ngsrik implementering av dr narsv rmar kr ver att systemutvecklare tar h nsyn till det bredare organisatoriska sammanhanget inklusive roller arbetsfl

den och samverkansbehov Detta holistiska tillvägagångssätt för utformningen av MSI system säkerställer att drifsvärmen inte bara uppfyller tekniska prestandakriterier såsom tillförlitlighet responsivitet och skalbarhet utan också överensstämmer med mänskliga och organisatoriska behov vilket underlättar deras införande och effektiv användning i en mängd olika tillämpningsscenarier Verklaras dessa forskningsbidrag avsedda att verbrygga gapet mellan teoretiska modeller för svärmsstyrning och praktisk implementering och därmed avancera och förnya borden MSI området och den bredare användningen av svärms teknologier

Experimental Methodology for Human-Robot Interaction Leimin Tian, Tina L.Y. Wu, Nicole L. Robinson, Pamela Carreno-Medrano, Wesley P. Chan, Maram Sakr, Elahe Abdi, Elizabeth A. Croft, Dana Kulić, 2025-06-30

Leading figures in Australian robotics research provide an overview and guidance for human robot interaction HRI experimental design and evaluation methodologies that consider the ethical implications of the research and its applications from a human centred and contextual perspective The authors explain introductory and advanced topics in HRI with a focus on human centred evaluation and ethical practices They also provide an online interactive checklist tool for novice HRI researchers and students to deploy when designing their own studies The book is structured into three parts In Part I the authors first review fundamental methodologies and provide an interactive checklist tool of the HRI experimental study life cycle to guide beginners to the field Part II introduces an expanded set of approaches to support researchers and practitioners to create high quality study designs that draw on practices from human computer interaction human centred artificial intelligence psychology and social science and advance ethical HRI research Finally in Part III the authors discuss a selection of HRI studies as examples of how the introduced methodologies are adopted which will support the readers to further understand the fundamental and advanced methodologies described in Parts I and II The diverse collection of case studies enables readers to grasp the state of the art and apply what they have learned in their own practices This book is a vital resource for both students new to the field and experienced researchers and practitioners The book's practical focus and clear elucidation of relevant case studies from its introduction to the HRI experimental study life cycle through to advanced methods emerging in the field ensures that this will greatly benefit progress in the field with human centred and ethical experimental methodology

*Experimental IR Meets Multilinguality, Multimodality, and Interaction* Lorraine Goeuriot, Philippe Mulhem, Georges Quénot, Didier Schwab, Giorgio Maria Di Nunzio, Laure Soulier, Petra Galuščáková, Alba García Seco de Herrera, Guglielmo Faggioli, Nicola Ferro, 2024-09-18

The two volume set LNCS 14958 14959 constitutes the proceedings of the 15th International Conference of the CLEF Association CLEF 2024 held in Grenoble France during September 9 12 2024 The proceedings contain 11 conference papers 6 best of CLEF 2023 Labs papers and 14 Lab overview papers accepted from 45 submissions In addition an overview paper on the CLEF activities in the last 25 years is included The CLEF conference and labs of the evaluation forum deal with topics in information access from different perspectives in any modality and language focusing on experimental information retrieval

IR Human-Computer Interaction: Interaction

Modalities and Techniques Masaaki Kurosu, 2013-07-01 The five volume set LNCS 8004 8008 constitutes the refereed proceedings of the 15th International Conference on Human Computer Interaction HCII 2013 held in Las Vegas NV USA in July 2013 The total of 1666 papers and 303 posters presented at the HCII 2013 conferences was carefully reviewed and selected from 5210 submissions These papers address the latest research and development efforts and highlight the human aspects of design and use of computing systems The papers accepted for presentation thoroughly cover the entire field of human computer interaction addressing major advances in knowledge and effective use of computers in a variety of application areas This volume contains papers in the thematic area of human computer interaction addressing the following major topics speech natural language and auditory interfaces gesture and eye gaze based Interaction touch based interaction haptic interaction graphical user interfaces and visualisation

*Minor-element Interactions in Copper Matte Smelting*, 1984  
*A Technical Description of the Large Area Crop Inventory Experiment (LACIE)*, 1979  
*Telemanipulator and Telepresence Technologies*, 2001  
**Progress in Robotics** Jong-Hwan Kim, Shuzhi Sam Ge, Prahlad Vadakkepat, Norbert Jesse, Abdullah Al Mamun, Sadasivan Puthusserypady, Ulrich Rückert, Joaquin Sitte, Ulf Witkowski, Ryohei Nakatsu, Thomas Braunl, Jacky Baltes, John Anderson, Ching-Chang Wong, David Ahlgren, 2009-08-19 th This volume is an edition of the papers selected from the 12 FIRA RoboWorld Congress held in Incheon Korea August 16 18 2009 The Federation of International Robosoccer Association FIRA www.fira.net is a non profit organization which organizes robotic competitions and meetings around the globe annually The RoboSoccer competitions started in 1996 and FIRA was established on June 5 1997 The Robot Soccer competitions are aimed at promoting the spirit of science and technology to the younger generation The congress is a forum in which to share ideas and future directions of technologies and to enlarge the human networks in robotics area The objectives of the FIRA Cup and Congress are to explore the technical development and achievement in the field of robotics and provide participants with a robot festival including technical presentations robot soccer competitions and exhibits under the theme Where Theory and Practice Meet th Under the umbrella of the 12 FIRA RoboWorld Incheon Congress 2009 six international conferences were held for greater impact and scientific exchange th 6 International Conference on Computational Intelligence Robotics and Autonomous Systems CIRAS th 5 International Symposium on Autonomous Minirobots for Research and Edutainment AMiRE International Conference on Social Robotics ICSR International Conference on Advanced Humanoid Robotics Research ICAHRR International Conference on Entertainment Robotics ICER International Robotics Education Forum IREF This volume consists of selected quality papers from the six conferences

*Interactive Robotic Aids*, 1986  
*Digital Media, Projection Design, and Technology for Theatre* Alex Oliszewski, Daniel Fine, Daniel Roth, 2025-01-30 Digital Media Projection Design converging and blending projectors projection mapping calculating surface brightness luminance screen size and throw distance and more making this a complete guide to digital media and projection design today The second edition is updated with new content throughout and two new chapters addressing the latest technologies and trends

in virtual performance motion capture generative AI and VR AR Ten new case studies from diverse practitioners have been added and the book is restructured with shorter chapters for easier navigation and reference This book serves well as a main or supplemental textbook for courses in projection design theatre and digital media design It is also useful for emerging practitioners Sample assets and interviews with leading projection designers are available for download at [www.routledge.com/9781032302157](http://www.routledge.com/9781032302157)

Report of Investigations, 1984

**Proceedings of the 62nd Conference of Metallurgists, COM 2023** Metallurgy & Materials Soc. of CIM, 2023-10-19 These Proceedings represent the metallurgical engineering and materials science research presented at the 62nd Annual Conference of Metallurgists COM 2023 held in Toronto Canada from 21 to 24 August 2023 The Annual Conference of Metallurgists is organized by the Metallurgy Materials Society of the Canadian Institute of Mining Metallurgy and Petroleum MetSoc of CIM The collection themed Climate Change and Sustainability presents findings on a wide range of topics including Advanced Manufacturing and Materials Sustainability Integration for Better Outcomes Light Metals for Transportation and Next Generation Vehicles Derek Kerfoot Memorial Pressure Hydrometallurgy Symposium Laplante Laskowski Symposium on Mineral Processing Fundamentals Wasmund Memorial Symposium of Sustainability in Pyrometallurgy

*The Century of Space Science* J.A. Bleeker, Johannes Geiss, M. Huber, 2012-12-06 One of the most attractive features of the young discipline of Space Science is that many of the original pioneers and key players involved are still available to describe their field Hence at this point in history we are in a unique position to gain first hand insight into the field and its development To this end *The Century of Space Science* a scholarly authoritative reference book presents a chapter by chapter retrospective of space science as studied in the 20th century The level is academic and focuses on key discoveries how these were arrived at their scientific consequences and how these discoveries advanced the thoughts of the key players involved With over 90 world class contributors such as James Van Allen Cornelis de Jager Eugene Parker Reimar Lüst and Ernst Stuhlinger and with a Foreword by Lodewijk Woltjer past ESO Director General this book will be immensely useful to readers in the fields of space science astronomy and the history of science Both academic institutions and researchers will find that this major reference work makes an invaluable addition to their collection

**Computational Design Methods and Technologies: Applications in CAD, CAM and CAE Education** Gu, Ning, Wang, Xiangyu, 2012-01-31 The emergence and adoption of computational technologies has significantly changed design and design education beyond the replacement of drawing boards with computers or pens and paper with computer aided design CAD computer aided manufacturing CAM and computer aided engineering CAE applications

*Computational Design Methods and Technologies Applications in CAD CAM and CAE Education* explores state of the art developments in computational design methods and their impact on contemporary design education Readers will find case studies empirical research findings pedagogical theories and reflections Researchers educators designers and developers will better understand how applying pedagogical research and reflection has influenced and will continue to transform the field

in the future     **NASA Tech Briefs** ,1993-05     ERDA Energy Research Abstracts United States. Energy Research and Development Administration,1976     **Scientific and Technical Aerospace Reports** ,1995-08     List of Publications of the U.S. Army Engineer Waterways Experiment Station U.S. Army Engineer Waterways Experiment Station,1985     *Virtual, Augmented and Mixed Reality* Jessie Y. C. Chen,Gino Fragomeni,2025-05-30 This three volume set LNCS 15788 15790 constitutes the refereed proceedings of the 17th International Conference on Virtual Augmented and Mixed Reality VAMR 2025 held as part of the 27th International Conference on Human Computer Interaction HCII 2025 in Gothenburg Sweden during June 22 27 2025 The total of 1430 papers and 355 posters included in the HCII 2025 proceedings were carefully reviewed and selected from 7972 submissions The papers presented in these three volumes are organized in the following topical sections Part I Designing and Developing Virtual Environments UX in Virtual Environments Part II VR Culture Art and Entertainment Social Interaction and Wellbeing in Virtual Environments Part III VR Games Virtual Environments for Learning Training and Professional Development Multimodal Interaction in Virtual Environments



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