Mohieddine Jelali
and Andreas Kroll

Hydraulic Servo-systems

Modelling, Identification and Control

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ADVANCES IN INDUSTRIAL CONTROL

Hydraulic Servosystems Modelling Identification And Control

Axaykumar Mehta,Bijnan Bandyopadhyay

Hydraulic Servosystems Modelling Identification And Control:

Hydraulic Servo-systems Mohieddine Jelali,Andreas Kroll,2012-12-06 Hydraulic Servo systems details the basic concepts of many recent developments of nonlinear identification and nonlinear control and their application to hydraulic servo systems developments such as feedback linearisation and fuzzy control It also reviews the principles benefits and limitations associated with standard control design approaches such as linear state feedback control feedforward control and compensation for static nonlinearities because of their continued practical importance Featuring theoretical physically based modelling of hydraulic servo systems experimental modelling system identification control strategies for hydraulic servo systems case studies and experimental results Appendices outline the most important fundamentals of nonlinear differential geometry and fuzzy control The book is very application oriented and provides the reader with detailed working procedures and hints for implementation routines and software tools **Proceedings of the 16th International Conference on Modelling, Identification and Control (ICMIC2024)** Qiang Chen,Tingli Su,Peng Liu,Weicun Zhang,2025-03-02 This book includes original peer reviewed research papers from the 16th International Conference on Modelling Identification and Control ICMIC2024 held in Datong Shanxi China on Aug 9 11 2024 The topics covered include but are not limited to System Identification Linear Nonlinear Control Systems Data driven Modelling and Control Process Modelling and Process Control Fault Diagnosis and Reliable Control Intelligent Systems and Machine Learning and Artificial Intelligence The papers showcased here share the latest findings on methodologies algorithms and applications in modelling identification and control integrated with Artificial Intelligence AI making the book an asset for researchers engineers and university students alike Mechatronics 2017 - Ideas for Industrial Applications Jerzy Świder,Sławomir Kciuk,Maciej Trojnacki,2019-03-27 This book is devoted to the latest research results obtained by scientists and practitioners who work on the development and applications of mechatronics in particular in industrial practice The topics included in the book cover such areas and issues as measurement techniques in phenomena and mechatronic problems robotics and design of mechatronic systems research and application of mechatronics in medicine and sports modern applications of mechatronics in rapidly changing modern mining which puts strict demands on safety of people and the environment application of mechatronics in the automotive industry in the design and production process of modern cars defense technologies extremely demanding aerospace industry contemporary food industry as well as didactics of mechatronics lead at different universities in the paradigm of Industry 4 0

Proceedings of the 11th International Conference on Modelling, Identification and Control (ICMIC2019) Rui Wang,Zengqiang Chen,Weicun Zhang,Quanmin Zhu,2019-12-03 This book includes original peer reviewed research papers from the 11th International Conference on Modelling Identification and Control ICMIC2019 held in Tianjin China on July 13 15 2019 The topics covered include but are not limited to System Identification Linear Nonlinear Control Systems Data driven Modelling and Control Process Modelling and Process Control Fault Diagnosis and Reliable Control Intelligent

Systems and Machine Learning and Artificial Intelligence The papers showcased here share the latest findings on methodologies algorithms and applications in modelling identification and control integrated with Artificial Intelligence AI making the book a valuable asset for researchers engineers and university students alike *Gas Turbines Modeling, Simulation, and Control* Hamid Asgari,XiaoQi Chen,2015-10-16 Gas Turbines Modeling Simulation and Control Using Artificial Neural Networks provides new approaches and novel solutions to the modeling simulation and control of gas turbines GTs using artificial neural networks ANNs After delivering a brief introduction to GT performance and classification the book Outlines important criteria to consi *The 8th International Conference on Robotic, Vision, Signal Processing & Power Applications* Harsa Amylia Mat Sakim,Mohd Tafir Mustaffa,2014-07-08 The proceeding is a collection of research papers presented at the 8th International Conference on Robotics Vision Signal Processing and Power Applications ROVISP 2013 by researchers scientists engineers academicians as well as industrial professionals from all around the globe The topics of interest are as follows but are not limited to Robotics Control Mechatronics and Automation Vision Image and Signal Processing Artificial Intelligence and Computer Applications Electronic Design and Applications Telecommunication Systems and Applications Power System and Industrial Applications **Proceedings of DINAME 2017** Agenor de T. Fleury,Domingos A. Rade,Paulo R. G. Kurka,2018-07-20 This book presents the most significant contributions to the DINAME 2017 conference covering a range of dynamic problems to provide insights into recent trends and advances in a broad variety of fields seldom found in other proceedings volumes DINAME has been held every two years since 1986 and is internationally recognized as a central forum for discussing scientific achievements related to dynamic problems in mechanics Unlike many other conferences it employs a single session format for the oral presentations of all papers which limits the number of accepted papers to roughly 100 and makes the evaluation process extremely rigorous The papers gathered here will be of interest to all researchers graduate students and engineering professionals working in the fields of mechanical and mechatronics engineering and related areas around the globe **Proceedings of the 4th International Conference Engineering Innovations and Sustainable Development** Valentina Mantulenko,2025-07-10 This book presents the contributions from the 4th International Conference Engineering Innovations and Sustainable Development held in Samara Russia on February 27 2025 By presenting international research on various sustainability issues it includes topics such as current trends in industrial and agricultural development innovations in the construction and transport sectors problems concerning the financing of innovative activities and governmental support for innovations and engineering competences and skills in the era of new technologies It also covers the economic environmental and informational aspects of sustainable development in the context of innovations Finally the book addresses theoretical and practical aspects by studying the phenomenon of sustainability and engineering development in terms of comparing international experiences It provides significant value for scientists teachers and students of higher educational institutions and specialists who are researching

sustainable development issues in the era of engineering innovations *Emerging Trends in Sliding Mode Control* Axaykumar Mehta,Bijnan Bandyopadhyay,2020-12-21 This book compiles recent developments on sliding mode control theory and its applications Each chapter presented in the book proposes new dimension in the sliding mode control theory such as higher order sliding mode control event triggered sliding mode control networked control higher order discrete time sliding mode control and sliding mode control for multi agent systems Special emphasis has been given to practical solutions to design involving new types of sliding mode control This book is a reference guide for graduate students and researchers working in the domain for designing sliding mode controllers The book is also useful to professional engineers working in the field to design robust controllers for various applications **Advances in Hydraulic and Pneumatic Drives and Control 2020** Jarosław Stryczek,Urszula Warzyńska,2020-10-18 This book reports on cutting edge research and technical achievements in the field of hydraulic drives The chapters selected from contributions presented at the International Scientific Technical Conference on Hydraulic and Pneumatic Drives and Controls NSHP 2020 held on October 21 23 2020 in Trzebieszowice Poland cover a wide range of topics such as theoretical advances in fluid technology work machines in mining construction marine and manufacturing industry and practical issues relating to the application and operation of hydraulic drives Further topics include safety and environmental issues associated with the use of machines with hydraulic drive and new materials in design of hydraulic components A special emphasis is given to new solutions for hydraulic components and systems as well as to the identification of phenomena and processes occurring during the operation of hydraulic and pneumatic systems *On Motion Control of Linear Incremental Hydraulic Actuators* Martin Hochwallner,2017-10-24 Linear Incremental Hydraulic Actuators combine one or more short stroke cylinders and two or more engaging disengaging mechanisms into one actuator with long medium or even unlimited stroke length The motion of each single short stroke actuator concatenated by the engaging disengaging mechanisms forms the motion of the linear incremental hydraulic actuator The patterns of how these motions are concatenated form the gaits of a specific linear incremental hydraulic actuator Linear incremental hydraulic actuators may have more than one gait In an application the gaits may be combined to achieve optimal performance at various operating points The distinguishing characteristic of linear incremental hydraulic actuators is the incremental motion The term incremental actuator is seen as analogous to the incremental versus absolute position sensor Incremental actuators realize naturally relative positioning Incremental motion means also that the behavior does not depend on an absolute position but only on the relative position within a cycle or step Incremental actuators may realize discrete incremental or continuous incremental motion Discrete incremental actuators can only approach discrete positions whereby stepper drives are one prominent example In contrast continuous incremental actuators may approach any position Linear electric motors are one example of continuous incremental actuators The actuator has no inherent limitation in stroke length as every step or cycle adds only to the state at the beginning of the step or cycle and does not depend on the

absolute position This led to the alternative working title Hydraulic Infinite Linear Actuator Linear incremental hydraulic actuator provides long stroke high force and linear motion and has the potential to decrease the necessary resource usage minimize environmental impact e g from potential oil spillage extend the range of feasible products longer stiffer better etc This thesis presents an analysis of the characteristics and properties of linear incremental hydraulic actuators as well as the gaits and possible realizations of some gaits The gait for continuous smooth motion with two cylinders is comprehensively studied and a control concept for the tracking problem is proposed The control concept encapsulates the complexity of the linear incremental hydraulic actuator so that an application does not have to deal with it One other gait the ballistic gait which realizes fast energy efficient motion enabling energy recuperation is studied *Electro-Hydraulic Actuation Systems* J. Jaidev Vyas,Balamurugan Gopalsamy,Harshavardhan Joshi,2018-09-01 The book serves as a unique integrated platform which not only describes the design methodology of electro hydraulic actuation systems but also provides insights into the design of the servo valve which is the most important component in the system It presents a step by step design process comparative tables illustrative figures and detailed explanations The book focuses on the design and testing of electro hydraulic actuation systems which are increasingly being used in motion control applications particularly in those where precision actuation at high operational rates is of prime importance It describes in detail the design philosophy of such high performance systems presenting a system used as a physical test setup together with experimental results to corroborate the calculations Of particular interest are the electro hydraulic servo valves that form the heart of these actuations These valves are complex and not much data is available in open literature due to OEM propriety issues In this context the book discusses the elaborate mathematical models that have been derived and an approach to validate the mathematical models with test results Presenting the complex methodology in simple language it will prove to be a valuable resource for students researchers and professional engineers alike **Linking Models and Experiments, Volume 2** Tom Proulx,2025-08-07 Linking Models and Experiments Volume 2 Proceedings of the 29th IMAC A Conference and Exposition on Structural Dynamics 2011 the second volume of six from the Conference brings together 33 contributions to this important area of research and engineering The collection presents early findings and case studies on fundamental and applied aspects of Structural Dynamics including papers on Finite Element Techniques Model Updating Experimental Dynamics Substructuring Model Validation and Uncertainty Quantification **Variable-Structure Approaches** Andreas Rauh,Luise Senkel,2016-05-17 This edited book aims at presenting current research activities in the field of robust variable structure systems The scope equally comprises highlighting novel methodological aspects as well as presenting the use of variable structure techniques in industrial applications including their efficient implementation on hardware for real time control The target audience primarily comprises research experts in the field of control theory and nonlinear dynamics but the book may also be beneficial for graduate students **Visual Servoing in Robotics** Jorge Pomares,2021-08-31 Visual servoing is a

well known approach to guide robots using visual information Image processing robotics and control theory are combined in order to control the motion of a robot depending on the visual information extracted from the images captured by one or several cameras With respect to vision issues a number of issues are currently being addressed by ongoing research such as the use of different types of image features or different types of cameras such as RGBD cameras image processing at high velocity and convergence properties As shown in this book the use of new control schemes allows the system to behave more robustly efficiently or compliantly with fewer delays Related issues such as optimal and robust approaches direct control path tracking or sensor fusion are also addressed Additionally we can currently find visual servoing systems being applied in a number of different domains This book considers various aspects of visual servoing systems such as the design of new strategies for their application to parallel robots mobile manipulators teleoperation and the application of this type of control system in new areas Detection and Diagnosis of Stiction in Control Loops Mohieddine Jelali,Biao Huang,2009-10-13 In the process industries stiction is the most common performance limiting valve problem and over the last decade numerous different techniques for overcoming it have been proposed This book represents a comprehensive presentation of these methods including their principles assumptions strengths and drawbacks Guidelines and working procedures are provided for the implementation of each method and MATLAB based software can be downloaded from www ualberta ca bhuang stiction book enabling readers to apply the methods to their own data Methods for the limitation of stiction effects are proposed within the general context of oscillation detection in control loops stiction detection diagnosis and stiction quantification and diagnosis of multiple faults The state of the art algorithms presented in this book are demonstrated and compared in industrial case studies of diverse origin chemicals building mining pulp and paper mineral and metal processing

Control Performance Management in Industrial Automation Mohieddine Jelali,2012-10-31 Control Performance Management in Industrial Automation provides a coherent and self contained treatment of a group of methods and applications of burgeoning importance to the detection and solution of problems with control loops that are vital in maintaining product quality operational safety and efficiency of material and energy consumption in the process industries The monograph deals with all aspects of control performance management CPM from controller assessment minimum variance control based and advanced methods to detection and diagnosis of control loop problems process non linearities oscillations actuator faults to the improvement of control performance maintenance re design of loop components automatic controller re tuning It provides a contribution towards the development and application of completely self contained and automatic methodologies in the field Moreover within this work many CPM tools have been developed that goes far beyond available CPM packages Control Performance Management in Industrial Automation presents a comprehensive review of control performance assessment methods develops methods and procedures for the detection and diagnosis of the root causes of poor performance in complex control loops covers important issues that arise when applying these assessment and

diagnosis methods recommends new approaches and techniques for the optimization of control loop performance based on the results of the control performance stage and offers illustrative examples and industrial case studies drawn from chemicals building mining pulp and paper mineral and metal processing industries This book will be of interest to academic and industrial staff working on control systems design maintenance or optimisation in all process industries Advances in Robot Design and Intelligent Control Aleksandar Rodić,Theodor Borangiu,2016-11-26 This book presents the proceedings of the 25th International Conference on Robotics in Alpe Adria Danube Region RAAD 2016 held in Belgrade Serbia on June 30th July 2nd 2016 In keeping with the tradition of the event RAAD 2016 covered all the important areas of research and innovation in new robot designs and intelligent robot control with papers including Intelligent robot motion control Robot vision and sensory processing Novel design of robot manipulators and grippers Robot applications in manufacturing and services Autonomous systems humanoid and walking robots Human robot interaction and collaboration Cognitive robots and emotional intelligence Medical human assistive robots and prosthetic design Robots in construction and arts and Evolution education legal and social issues of robotics For the first time in RAAD history the themes cloud robots legal and ethical issues in robotics as well as robots in arts were included in the technical program The book is a valuable resource for researchers in fields of robotics engineers who implement robotic solutions in manufacturing services and healthcare and master s and Ph D students working on robotics projects **Advances in Renewable Energies Offshore** Carlos Guedes Soares,2018-10-03 Advances in Renewable Energies Offshore is a collection of the papers presented at the 3rd International Conference on Renewable Energies Offshore RENEW 2018 held in Lisbon Portugal on 8 10 October 2018 The 104 contributions were written by a diverse international group of authors and have been reviewed by an International Scientific Committee The book is organized in the following main subject areas Modelling tidal currents Modelling waves Tidal energy devices design applications and experiments Tidal energy arrays Wave energy devices point absorber multibody applications control experiments CFD coastal OWC OWC and turbines Wave energy arrays Wind energy devices Wind energy arrays Maintenance and reliability Combined platforms Moorings and Flexible materials Advances in Renewable Energies Offshore collects recent developments in these fields and will be of interest to academics and professionals involved in the above mentioned areas **Proceedings of the International Conference of Mechatronics and Cyber- MixMechatronics - 2020** Gheorghe Ion Gheorghe,2020-07-17 This book presents state of the art research in the field of mechatronics and cyber mixmechatronics gathering papers from almost all continents Featuring contributions by research scholars in both government financed institutions and in the business environment it offers a clear picture of the innovations emerging in the field The book is not limited to mechatronics but also covers all the smart technical sciences and discusses promising medical applications based on nanotechnologies As such it is a valuable resource for students wanting to learn from leading scholars as well as for researchers in all areas of engineering

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